



# eqss™ Gen-3 LMS Telehandler Load Management System

## Installation Manual for MLT735 / MLT730



**WARNING!**  
DO NOT HIGH PRESSURE  
WASH ANY OF THE GEN3  
COMPONENTS. FAILURE TO  
FOLLOW THIS WARNING  
WILL VOID WARRANTY

**\*\*\*Do Not Swap Components between Gen3-LMS kits\*\*\***

**When installing multiple Gen3-LMS kits, make sure the serial number on the sticker matches the serial number on the machine.**

**\*\*\*Failure To Follow Installation Manual Will Void Warranty\*\*\***

## Documentation Conventions

The list below highlights important documentation conventions.



Text presented in this manner is intended to provide the user with some general information. The user should ensure information presented in this manner is clearly understood.



Text presented in this manner provides the user with information to assist in completion of the current procedure being explained.



Text presented in this manner indicates that a failure to follow directions could result in damage to equipment, loss of information, bodily harm, or loss of life.

## **Important Information**

Information contained in this publication regarding this device's applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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# Tools Required for Installation

The tools required to perform the installation of the Gen3-LMS are listed below

- Pencil or Texta
- Drill
- Drill bits
  - 3.3 mm
  - 4.5 mm
  - 5 mm
  - 6.25 mm
  - 6.8 mm
  - 8.5 mm
- Centre punch
- Tap T-Handle
- Taps
  - M6
  - M7 x 0.75
  - M8
- Drill and tap oil
- Metric Allen keys
- Phillips Head screw driver
- Spanners and sockets
  - 7 mm
  - 10 mm
  - 13 mm
- Loctite thread locker
- Side cutters
- Stanley knife
- Crimpers
- Wire strippers

# Installation Index

The components and cables of the Gen-3 Telehandler Load Management System are outline in the tables below. The following pages show where the components are installed and the cable routing.

See the appropriate manual section for a detailed installation description for each component.



Refer to this section for any component placement or cable routing issues

<i>Item</i>	<i>Component Description</i>
1	Cable Reeler
2	Main Lift Cylinder Pressure Sensors
3	Compensation Cylinder Pressure Sensors
4	Can Pressure Input Module (CPIM)
5	Forward Camera
6	Light Tower
7	Rear Camera
8	Can Cabin Interface Module (CCIM)
9	Display Module
10	SPU Module
11	Stabiliser Connections
12	Joystick Connections (X43)

Table 1: Component Installation Index

<i>Colour</i>	<i>Cable Description</i>
Yellow	Boom Cable
Dark Green	Main Cylinder Pressure Sensor Cables
Dark Blue	Compensation Cylinder Pressure Sensors Cables
Light Blue	Forward Camera Cable
Violet	Signal Light Cable
Aqua	Rear Camera Cable
Dark Purple	CCIM Cable
Light Green	Cutout Harness
Red	Display Cable
Orange	User Control Cable
Brown	Machine Input Harness
Dark Yellow	Stabiliser Harness

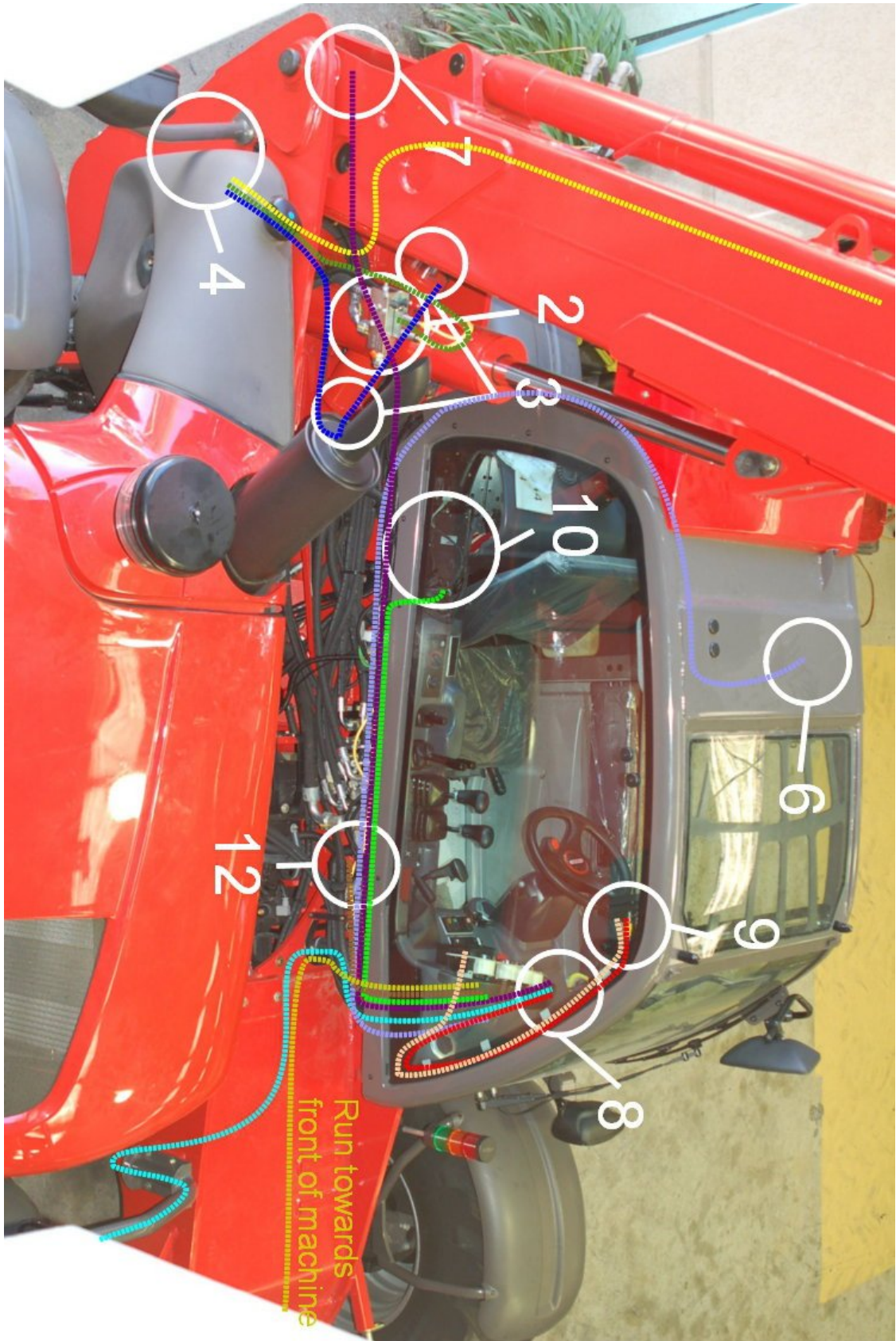
*Table 2: Cable Installation Index*





Cable tie to  
hydraulic lines

Illustration 1: Machine Boom








*Illustration 2: Machine Chassis*

Note: The old light tower is shown

# Covers

Remove the following covers before starting the installation

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	Remove the top and lower rear cover behind the boom.	
1.	Remove the side panel next to the cabin under the boom.	
2.	Inside the cabin remove the dashboard.	

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
3.	Remove the cover over the fluid containers	
4.	Remove the cover over the SPU behind the seat	

*Table 3: Cover removal*



# Cable Reeler Installation

The cable reeler is used to measure the boom extension to determine the maximum lifting capacity.




A false N07 fault can occur if the boom jumps off the stow switch due to pressurising the hydraulic system and without operating the boom extension control. Ensure the stow switch arm is correctly adjusted to prevent this error.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Drill and tap the holes for the cable reeler according to the mounting diagram on page 15.</p> <p>Mount using the supplied standoffs, bolts and washers.</p>	
2.	<p>Drill and tap an M8 hole for the cable anchor. Ensure the cable anchor is positioned so the cable runs in line with the boom.</p> <p>Mount the cable anchor and attach the cable.</p>	
3.	<p>Drill and tap the M6 holes for the stow switch trigger bracket.</p> <p>Mount the stow switch trigger bracket using the supplied M6 x 12 mm bolts and washers.</p> <p>Adjust the length of the trigger plate to ensure the stow switch is pressed when the boom is retracted.</p>	

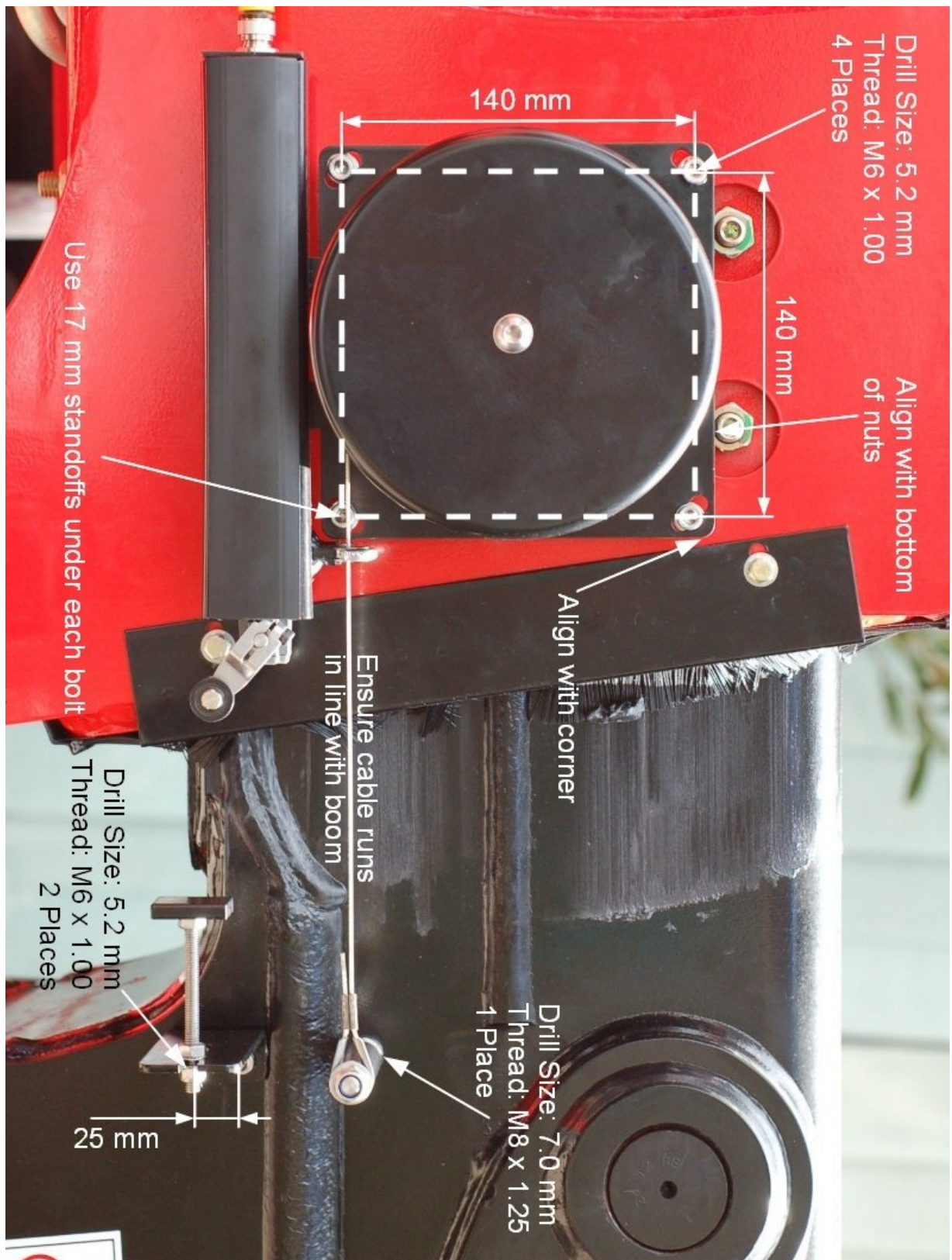
<i>Step</i>	<i>Description</i>	<i>Diagram</i>
4.	Connect the supplied M12 10 metre cable (CB001027) into the cable reeler connection.	
5.	<p>Run the cable along the hydraulic pipes running down the boom, secure using cable ties every 150 mm to 200 mm.</p> <p>Cable tie to the flexible hydraulic hoses down to the chassis. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.</p> <p>Run the remainder of the cable out the hole below the lift cylinder towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 29.</p>	

*Table 4: Cable Reeler Installation*



For further details on running the boom cable refer to the Installation Index on page 7

# Cable Reeler Mounting Position




*Illustration 3: Cable Reeler Mounting Position*

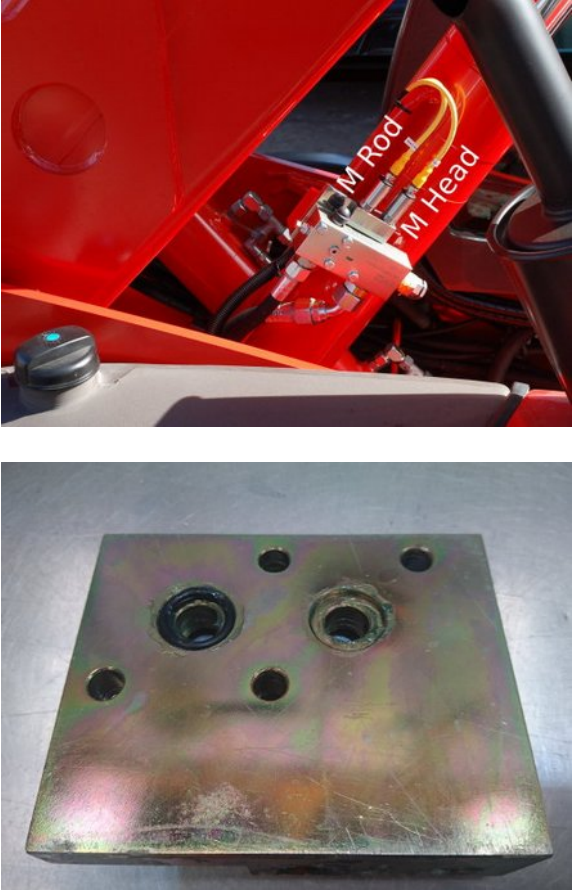
# Pressure Sensor Installation

The hydraulic pressure sensors are used to measure the lifting load of the telehandler.

## Pressure Manifold



Failure to tighten the bolts to the correct torque on the pressure manifold may result in a pressure failure on the counterbalance valve causing an uncontrolled fall of the boom.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Raise the boom to approximately 40 degrees.</p> <p>Support and secure the boom using an A Frame or similar apparatus. <b>It must support at least 2 tons.</b></p> <p>Apply the handbrake and insert chock under wheels.</p> <p>Remove the counterbalance valve on the side of the hydraulic lifting ram.</p> <p><b>Removing the counterbalance valve will release the hydraulic pressure which may result in a spray of oil.</b></p> <p>Secure the pressure manifold using the supplied 70 mm bolts and seals. Tighten the bolts for the manifold to <b>25 NM</b> using a torque wrench.</p> <p><b>Start the machine, pressurise the boom and check for leaks.</b></p>	 <p>Use lube on seals to hold in place during mounting</p>





<i>Step</i>	<i>Description</i>	<i>Diagram</i>
2.	<p>Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.</p> <p>Add both cables to 3 m of snake tube. Cable tie to the flexible hydraulic hoses connected to the main lift cylinder. Make sure the cable isn't pinched or stretched when the boom is raised or lowered.</p> <p>Run the remainder of the cable out the hole above the rear axle under the lift cylinder towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 29.</p> <p><b>Ensure the pressure sensors and cables do not collide with the boom and chassis structures and the cables do not stretch or pinch when the boom is raised and lowered.</b></p>	

Table 5: Pressure Manifold Installation



For further details on running the pressure sensor cables refer to the Installation Index on page 7

# Compensation Pressure Sensors

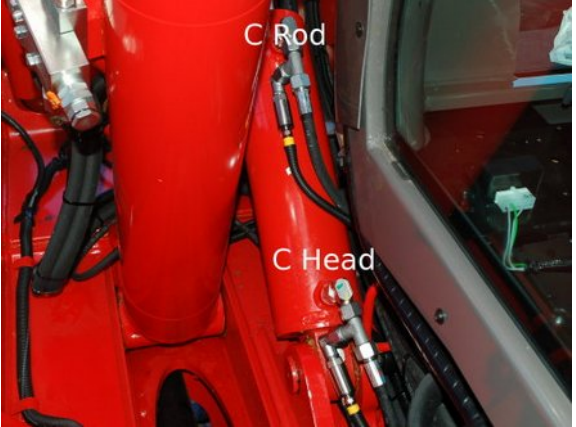
<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Install the pressure sensors with the tee connections into the head and rod of the compensation cylinder.</p> <p><b>Start the machine, pressurise the boom and check for leaks.</b></p> <p>Connect the supplied M12 4 metre cables (CB001026) into each of the pressure sensors.</p> <p>Add both cables to 3 m of snake tube.</p> <p>Run the remainder of the cable out the hole above the rear axle under the lift cylinder towards the rear of the machine and cable tie with the other cables during External Cable Completion on page 29.</p> <p><b>Ensure the pressure sensors and cables do not collide with the boom and chassis structures and the cables do not stretch or pinch when the boom is raised and lowered.</b></p>	 <p>View from behind the cabin towards the rear of the machine</p>


Table 6: Compensation Pressure Sensor Installation



For further details on running the pressure sensor cables refer to the Installation Index on page 7

# Reverse Camera

The rear camera video is displayed on the screen when the machine is in reverse gear to allow the operator to see behind the telehandler while reversing.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.



<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Drill a 31mm hole in the location shown.</p> <p>Insert the camera through the hole and adjust the angle using the alignment washers.</p> <p>Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032).</p> <p>Note; The white connector is not used.</p> <p>Secure the camera cable using a single cable tie to maintain the connector location.</p> <p>Run the remainder of the cable towards the cabin and cable tie with the other cables during External Cable Completion on page 29.</p>	
2.	<p>Place the supplied high pressure warning decal next to the reverse camera.</p>	

Table 7: Reverse Camera Installation



The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



Once the cable has secured with a cable tie disconnect the cable to remove the rear cover until the installation is finalised



For further details on running the camera cable refer to the Installation Index on page 7

# SPU Cable Harness



Isolate the main battery before connecting into the machine wiring

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Push the snake tube containing the terminal for the SPU connector cutout signal from under the boom through the hole into the cabin with the other snake tube cables for the SPU.</p> <p>Cable tie the snake tube into the existing tube going into the seal.</p>	
2.	<p>Remove the connectors from the SPU and insert the cutout terminal into B21 (where B is the larger connector)</p> <p>Cable tie to the SPU snake tube.</p>	
3.	<p>Run the snake tube and cables towards the cabin and cable tie with the other cables during External Cable Completion on page 29.</p>	

Table 8: SPU Cable Harness Installation



For further details on running the spu cable harness refer to the Installation Index on page 7

# Joystick Cable Harness



Isolate the main battery before connecting into the machine wiring

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Locate the connectors under the boom next to the cabin, that connect into the joystick.</p> <p>Connect the 12 pin tee connector from the machine input harness into the 12 pin connector into the joystick.</p> <p>Run the cable towards the cabin and cable tie with the other cables during External Cable Completion on page 29.</p>	

Table 9: Joystick Cable Harness Installation



For further details on running the joystick cable harness refer to the Installation Index on page 7

# Forward Camera

The forward camera video is displayed on the screen when the machine is in forward gear to allow the operator to see past the boom to obstructions that would damage the right front tyre.



Do not disconnect the camera power connection while the system is operating as this can damage the fuse.



<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Mount the camera to the side mirror using the p-clips as shown.</p> <p>Secure using two M6 nuts.</p>	
2.	<p>Connect the camera power and signal connectors to the supplied 5m camera cable (CB001032).</p> <p>Note; The white connector is not used.</p> <p>Run the cable along the same path as the headlight cable, run it through the headlight post, then under the chassis to the side of the cabin. Cable tie to the headlight cable every 150 mm to 200 mm.</p> <p>Complete the cable installation during External Cable Completion on page 29.</p>	

Table 10: Forward Camera Installation





The camera's viewing angle may need to be adjusted once the system is installed and the display is operational.



For further details on running the camera cable refer to the Installation Index on page 7


# Signal Light Installation

The signal light warns other workers when the telehandler is lifting loads close to its maximum capacity.



Ensure the power supply voltage is greater than 13.5V otherwise the signal light may not illuminate correctly.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	Mount the signal light on the top of the roof past the roof window towards the cabin door.	
2.	<p>Run the cable towards the boom side of the roof and push through the hole near the window wiper.</p> <p>Note: It might be necessary to cut a hole in the plastic roof cover to fit the cable.</p> <p>Run the cable under the cover towards the rear corner.</p>	

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
3.	<p>Run the cable along the pipes under the cover towards the chassis.</p> <p>Cable tie with the other cables during External Cable Completion on page 29.</p>	

*Table 11: Signal Light Installation*

# Can Pressure Input Module (CPIM)

The CPIM is responsible for processing the information sent from the pressure sensors.



Accidentally swapping the pressure sensor connections will not damage system and can be determined if the display is showing a negative load.



Do not plug the pressure sensor cable into the far right side boom cable. This will damage the system.


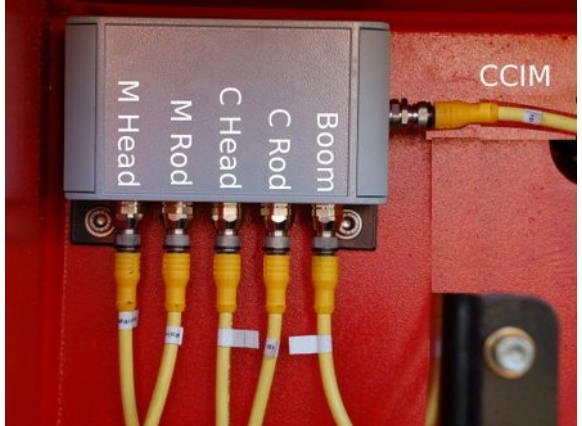

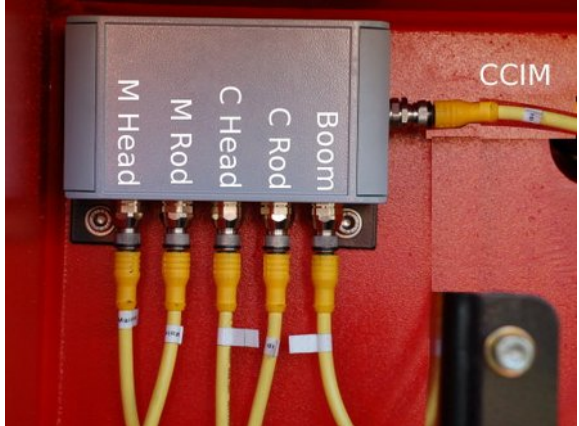

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Drill and tap two M8 holes for the CPIM bracket in the chassis rear panel.</p> <p>Mount using the supplied M8 x 12mm bolts and washers.</p>	
2.	<p>Connect the cables for the pressure sensors and boom cable to the CPIM according to the picture shown.</p> <p>Note: The CCIM cable will be installed during External Cable Completion on page 29.</p>	

Table 12: Can Pressure Input Module (CPIM) Installation

# External Cable Completion

All external cabling is completed in this step.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	Coil up and cable tie the additional cabling for the pressure sensor, and boom cables and store underneath the CPIM.	
2.	<p>Connect the supplied M12 4 metre cable (CB001026) into the connection out of the right side of the CPIM for the CCIM cable.</p> <p>Run the cable out the hole under the lift cylinder.</p>	
3.	Cable tie the CCIM, signal light, rear camera, cutout and machine input harnesses together along the side to the front of the cabin.	


<i>Step</i>	<i>Description</i>	<i>Diagram</i>
4.	<p>Run the CCIM, signal light, cutout harness, stabiliser cable harness and camera cables up through the hole into the cabin under the dashboard.</p> <p>Note: Pull the entire length of cable through into the cabin, excess cable will be stored under the dashboard cover in the cabin.</p>	

Table 13: External Cable Completion



For further details on running the cables refer to the Installation Index on page 7

# Display Installation

The display shows the current safety status of the telehandler.


<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Attach the display bracket to the level indicator in the top right corner using the supplied M6 x 35 mm bolts and nuts.</p> <p>Attach the display to the bracket and tighten the grub screw</p>	

Table 14: Display Installation



Adjust the display bracket for optimal viewing angle once the display is powered



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 46 for the correct method of attaching to the display connectors.



If the clip-on ferrites were removed from the CCIM and user control cables. See Appendix B: Reattach Ferrites and page 50 for the correct reattachment position.

# User Input Control

The user input control consists of a single switch mounted in the dashboard.


<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Drill a 39 mm hole into the dashboard in the location shown underneath the dashboard switches panel insert.</p> <p>Install the user input control dial in the dashboard, aligned so the Enter cap is facing up.</p>	

Table 15: User Input Control Installation



If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 46 for the correct method of attaching to the display connectors.



# Can Cabin Interface Module (CCIM)

The CCIM connects the system into the machine electronics.


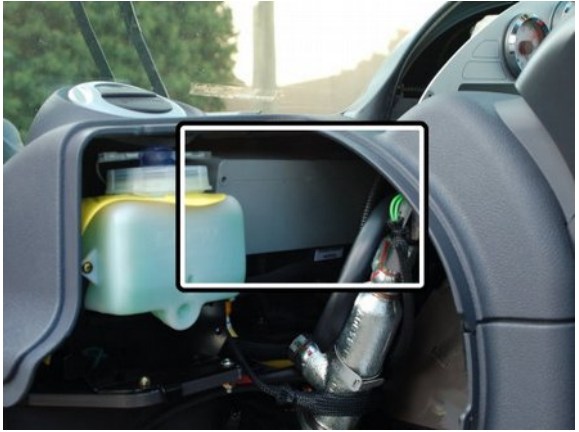


<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	Position the backup battery underneath the dashboard as shown and secure using double sided velcro tape.	
2.	<p>Position the CCIM next to the brake fluid container as shown and secure using double sided velcro tape.</p> <p>Remove the CCIM from the velcro to allow the connections to be completed. Reattach to the velcro in the section Finalisation on page 37.</p>	



Table 16: CCIM Installation

# Cabin Loom

The cabin loom connects the CCIM to the machine connections and the other modules of the system.

 Isolate the main battery before connecting into the machine wiring

 Do not disconnect the camera power connection while the system is operating as this can damage the fuse.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Connect the CCIM and signal light cables to the M12 connectors on the CCIM.</p> <p>Note: It doesn't matter which of the M12 connectors the CCIM and signal light cables are plugged into.</p>	
2.	<p>Connect the Power/Camera and IO Harnesses to the bulkhead connectors on the CCIM.</p>	

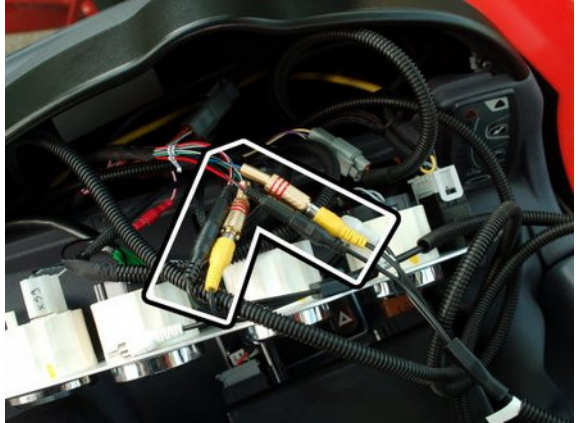



<i>Step</i>	<i>Description</i>	<i>Diagram</i>
3.	<p>Connect the camera power and signal cables to the cabin loom.</p> <p>Note: The white connector is not used.</p>	
4.	<p>Connect the 4 pin female connector from the machine input harness, the 6 pin female connector from the cutout cable harness and the 2 pin and 12 pin connectors from the stabiliser harness to the cabin loom connectors.</p> <p>Note: If stabilisers are not fitted leave the 2 and 12 pin disconnected</p>	
5.	<p>Run the 8 pin cable from the CCIM and 5 pin cable from the user control through the gap between the window and the dashboard.</p> <p>Run both cables through snake tube and attach to the connectors to the back of the display.</p>	
6.	<p>Place cable tie points on the side of the window.</p> <p>Cable tie the snake tube to the cable tie points.</p> <p>Connect the cables to the display. Do not over-tighten the connectors.</p>	

Table 17: Cabin Loom Installation




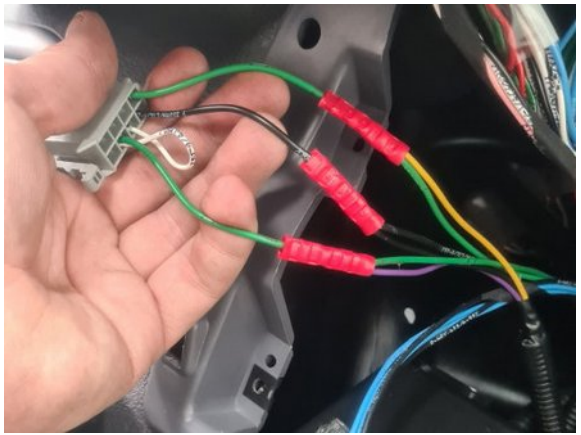

If the M12 screw lock connectors on the display are over tightened it will twist the connector pins attaching the connector to the PCB. See Appendix A: Attaching Display Connectors on page 46 for the correct method of attaching to the display connectors.







If the clip-on ferrites were removed from the CCIM and user control cables. See Appendix B: Reattach Ferrites and page 50 for the correct reattachment position.

# Finalisation

This section will complete the final power connections to power the system and finish any additional items.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>								
1.	<p>Cut wire 478 into terminal 1 of the switch.</p> <p>Join the yellow wire from the machine input harness to side of wire 478 leading towards the switch.</p> <p>Join the violet wire from the machine input harness to the other side of wire 478 leading towards the electronics.</p>									
2.	<p>Splice the wires from the power connector into the grey radio connector according to the table below.</p> <table border="1" data-bbox="306 1120 798 1265"> <thead> <tr> <th><u>Terminal #</u></th> <th><u>Wire Colour</u></th> </tr> </thead> <tbody> <tr> <td>8</td> <td>Black</td> </tr> <tr> <td>4</td> <td>Violet</td> </tr> <tr> <td>7</td> <td>Yellow</td> </tr> </tbody> </table> <p>Secure the splice joins using electrical tape</p> <p>Ensure the correct fuses are installed in the machine's cabin fuse box to enable the radio power.</p>	<u>Terminal #</u>	<u>Wire Colour</u>	8	Black	4	Violet	7	Yellow	 <p><b>Grey Radio Connector (Plug Side View)</b></p> 
<u>Terminal #</u>	<u>Wire Colour</u>									
8	Black									
4	Violet									
7	Yellow									

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
3.	<p>Connect the spade lug on the black wire to the negative (black) battery terminal.</p> <p>Connect the spade lug on the blue wire to the positive (red) battery terminal.</p>	
4.	<p>Attach the CCIM to the velcro strips installed earlier.</p>	
5.	<p>Coil up the extra cables and store underneath the dashboard cover.</p> <p>Reconnect the main battery from the isolation switch.</p> <p>Turn the machine onto first stage /accessories and ensure the system is activated.</p>	
6.	<p>Adjust the display bracket for optimal viewing</p> <p>Set the machine into forward gear to activate the forward camera. Adjust the forward camera so the front right wheel is visible.</p> <p>Set the machine into reverse gear to activate the reverse camera. Adjust the reverse camera so the video is level.</p>	

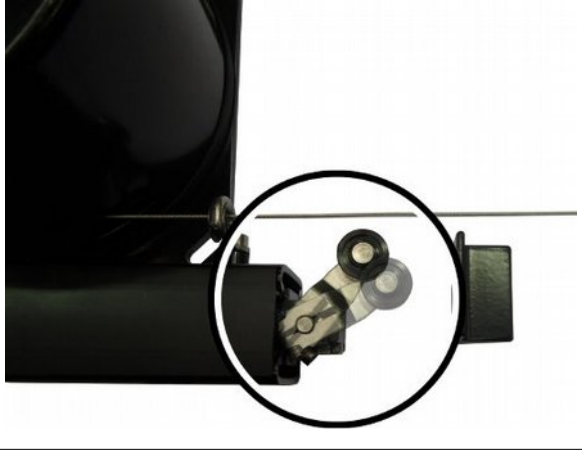


<i>Step</i>	<i>Description</i>	<i>Diagram</i>
7.	<p>Operate the boom movement controls to test if a false N07 fault occurs.</p> <p>If a N07 fault does occur, adjust the arm on the stow switch forwards towards the stow switch trigger.</p> <p>Note: The actual switch arm orientation may differ from the picture.</p>	
8.	<p>Perform a final check on all the cabling and sensors.</p> <p>Replace all the covers</p>	


Table 18: Finalisation

 Make sure to update the machine ECU software for Australian configuration using the Manitou pad.

 Complete the system checklist once installation has been completed.

# Set Time & Sensor Calibration

Once the installation is complete, the time will need to be set and the sensors will require calibration.



A sensor calibration must be performed once the cable reeler and CPIM have been mounted. If the cable reeler or CPIM have been moved/repositioned a recalibration must be performed

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Press Enter on the user control dial to enter the menu system.</p> <p>Press the arrow buttons to select System Menu.</p> <p>Press Enter to select the menu.</p>	<div style="border: 1px solid black; padding: 5px;"> <p style="text-align: center; margin: 0;"><b>Main Menu</b></p> <hr/> <p style="text-align: center; margin: 0;">Attachment Selection Menu</p> <div style="background-color: #4a7ebb; color: white; text-align: center; padding: 5px; margin: 5px 0;"> <p style="margin: 0;">System Menu</p> </div> <p style="text-align: center; margin: 0;">Exit Menu</p> <hr/> </div>
2.	<p>Select Advanced Menu</p>	<div style="border: 1px solid black; padding: 5px;"> <p style="text-align: center; margin: 0;"><b>System Menu</b></p> <hr/> <p style="text-align: center; margin: 0;">Volume / Brightness</p> <hr/> <p style="text-align: center; margin: 0;">Status Menu</p> <hr/> <p style="text-align: center; margin: 0;">Diagnostics Menu</p> <hr/> <p style="text-align: center; margin: 0;">System Tests</p> <div style="background-color: #4a7ebb; color: white; text-align: center; padding: 5px; margin: 5px 0;"> <p style="margin: 0;">Advanced Menu</p> </div> <p style="text-align: center; margin: 0;">Return to Main Menu</p> <hr/> </div>

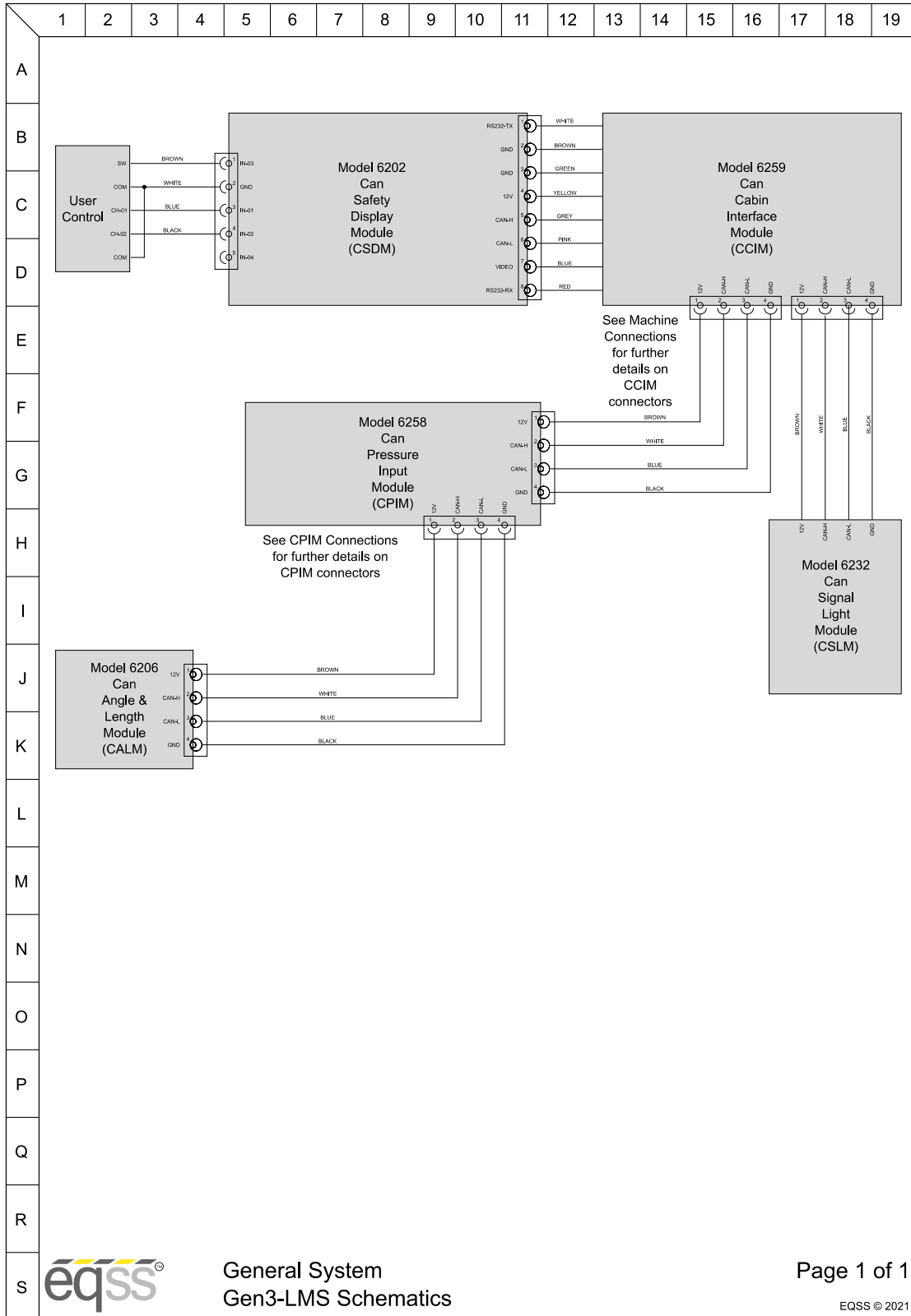


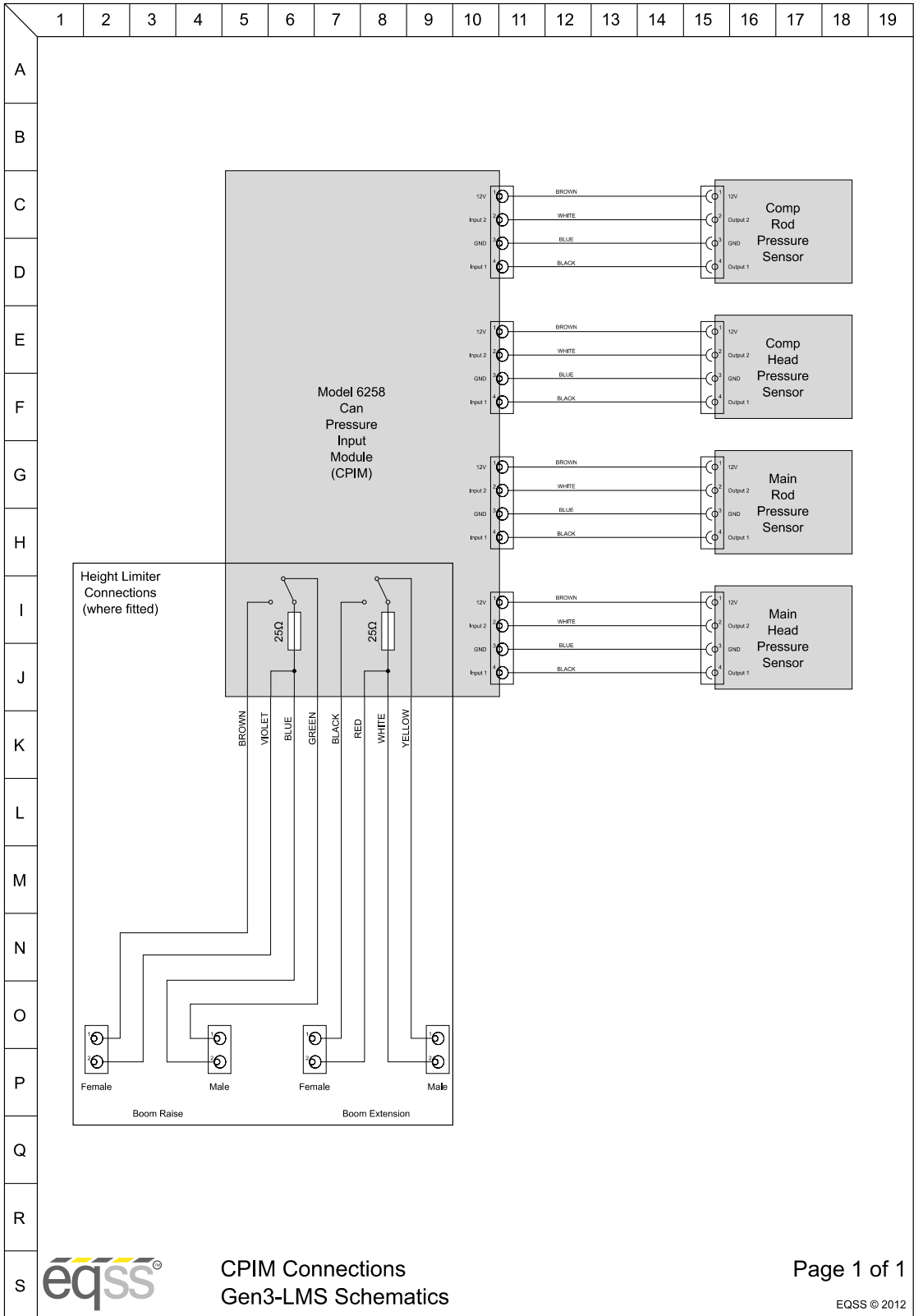
<i>Step</i>	<i>Description</i>	<i>Diagram</i>														
3.	Enter the password (Default Password: 2-8-4)	<table border="1"> <thead> <tr> <th colspan="2"><i>Enter Password</i></th> </tr> </thead> <tbody> <tr> <td>Number 1</td> <td>2</td> </tr> <tr> <td>Number 2</td> <td>8</td> </tr> <tr> <td>Number 3</td> <td>4</td> </tr> <tr> <td colspan="2">Submit Password</td> </tr> <tr> <td colspan="2">Return to System Menu</td> </tr> </tbody> </table>	<i>Enter Password</i>		Number 1	2	Number 2	8	Number 3	4	Submit Password		Return to System Menu			
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4.	Select Set Time / Date	<table border="1"> <thead> <tr> <th colspan="2"><i>Advanced Settings</i></th> </tr> </thead> <tbody> <tr> <td colspan="2">Set Time / Date</td> </tr> <tr> <td colspan="2">Sensor Calibrations</td> </tr> <tr> <td colspan="2">Change Language</td> </tr> <tr> <td colspan="2">Change Password</td> </tr> <tr> <td colspan="2">Return to System Menu</td> </tr> </tbody> </table>	<i>Advanced Settings</i>		Set Time / Date		Sensor Calibrations		Change Language		Change Password		Return to System Menu			
<i>Advanced Settings</i>																
Set Time / Date																
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5.	<p>Enter the correct time and date for your area.</p> <p>Press the arrow keys to select a time/date parameter</p> <p>Press Enter and the parameter will change to red, press the arrow keys to change the value and then press the Enter key to store the value.</p> <p>Note: The hour parameter is in 24 hour clock</p> <p>Repeat for the rest of the time values</p>	<table border="1"> <thead> <tr> <th colspan="2"><i>Set Time / Date</i></th> </tr> </thead> <tbody> <tr> <td>Hour</td> <td>15</td> </tr> <tr> <td>Minute</td> <td>54</td> </tr> <tr> <td>Day</td> <td>10</td> </tr> <tr> <td>Month</td> <td>2</td> </tr> <tr> <td>Year</td> <td>2016</td> </tr> <tr> <td>Region</td> <td>Melbourne</td> </tr> </tbody> </table>	<i>Set Time / Date</i>		Hour	15	Minute	54	Day	10	Month	2	Year	2016	Region	Melbourne
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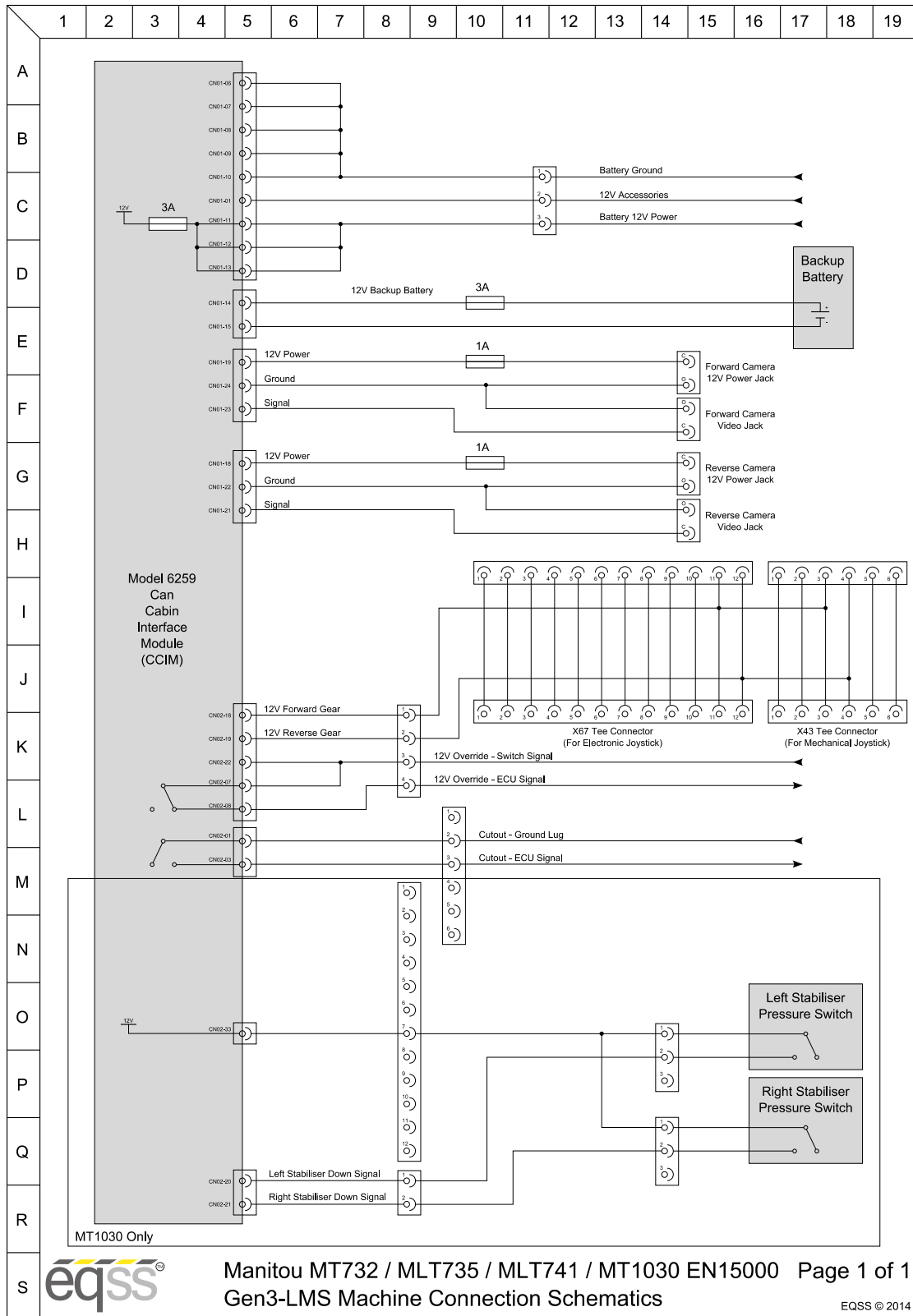
<i>Step</i>	<i>Description</i>	<i>Diagram</i>
6.	Scroll to the next page and select Save to store the new time/date and return to the Advanced Menu.	<p>The diagram shows a menu with a blue highlighted button labeled "Save" and a button below it labeled "Return to Advanced Menu".</p>
7.	Select Sensor Calibrations	<p>The diagram shows a menu titled "Advanced Settings" with options: "Set Time / Date", "Sensor Calibrations" (highlighted in blue), "Change Language", "Change Password", and "Return to System Menu".</p>
8.	Select Calibrate Carrier Angle and then follow the instructions on the screen to complete the calibration.  Repeat for Calibrate Boom Angle and Calibrate Boom Length.	<p>The diagram shows a menu titled "Sensor Calibration Menu" with options: "Calibrate Carrier Angle" (highlighted in blue), "Calibrate Boom Angle", "Calibrate Boom Length", and "Return to Advanced Menu".</p>

Table 19: Sensor Calibration

# Schematics







# Appendix A: Attaching Display Connectors

The procedure below describes the correct method of attaching the cables to the screw lock connectors on the display.



If the M12 screw lock connectors on the display are over tightened, it will twist the connector pins attaching the connector to the PCB.

<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Connect the cable from the user control to the top 5 pin connector on the display.</p> <p>Connect the cable from the CCIM to the bottom 8 pin connector on the display.</p>	
2.	<p>Line up the alignment hole on the cable connector with the alignment notch on the display connector.</p>	




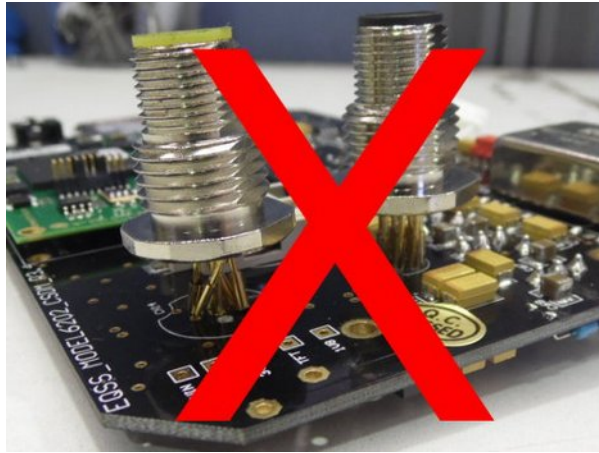
<i>Step</i>	<i>Description</i>	<i>Diagram</i>
3.	Push the female connector from the cable into the male connector on the display.	
4.	Rotate the nut on the female connector by hand in a clockwise direction, until the tension on the nut starts to increase.	
5.	Push the cable in again and repeat steps 3 and 4 until the connector is secure.	

Table 20: Install Display Connector Procedure



The method to correctly secure the cable is to push-twist-push-twist until the connector is fully inserted and secure. This will minimise the twisting force applied to the connector.

Below is a picture of a damaged connector on the PCB inside the display. This damaged occurred because the connector was over tightened.



*Illustration 4: Damaged Display Connector*



Do not use any tools to tighten the connector.



*Illustration 5: Do Not Use Tools To Tighten Connector*





Do not over-tighten the nuts on the back of the display connectors. These nuts should only be hand tightened. If the nuts are overtightened it will damage the PCB inside the display.




*Illustration 6: Do Not Over Tighten Nuts*



Damage to the display connectors is not covered under warranty.

# Appendix B: Reattach Ferrites

If the clip-on ferrites on the displays are removed during installation, they will need to be reattached as shown in the procedure below.

 If the ferrites are not reinstalled or attached in the specified location the Gen3-LMS kit will not meet the AS/NZS CISPR 22:2006 certification.

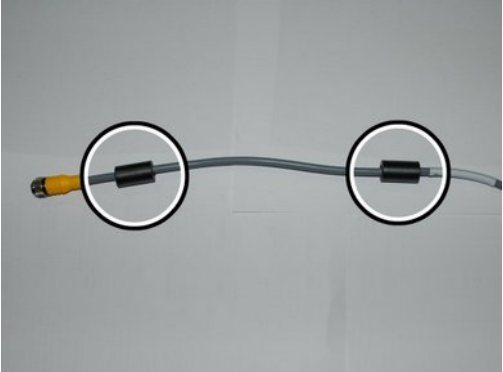
<i>Step</i>	<i>Description</i>	<i>Diagram</i>
1.	<p>Attach the two clip-on ferrites at a location of 60 mm and 260 mm from the start of the connector to the start of the ferrite.</p> <p>Do this for both the CCIM and user control cables that plug into the display.</p>	

Table 21: Reattach Ferrites Procedure

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**Equipment Safety Systems Pty. Ltd.** ABN: 31 061 789 151  
75 Naxos Way, Keysborough 3173, Victoria, Australia

Tel: +61 3 8770 6555  
Fax: +61 3 8770 6590  
Web: [www.eqss.com.au](http://www.eqss.com.au)