

2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Installation Manual

eqss

**Genie Smartlink** 

Document # DO001205

# EQSS Model6253 – OverWatch™ Genie Smartlink Series





Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

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DOCUMENT ABSTRACT: This Installation Manual details the manufac scissor lift equipped with a Smartlink operat		ons for installing the Model6253 OverWatch	on a Genie
PRODUCT NAME: Model6253 OverWatch Operator Detection	System		
REFERENCE DOCUMENTS: DO001195 Model6253 OverWatch User Ma	nual		
CURRENT DOCUMENT REVISION: 2.6			
<ul> <li>REVISION INFORMATION:</li> <li>1.1 Initial Document Creation for system installation on the Genie SmartLink series machines</li> <li>1.2 Update of instructions of soldering connections to PCB and securing connections via P-clip</li> <li>2.0 Update of instructions to work with Plug and Play Loom AS001928</li> <li>2.1 Modified Ø3.2mm through holes to Ø4.0mm</li> <li>2.2 Update on PCB installation images and inclusion of harness schematics</li> <li>2.3 Update on Plug and play board and new sensor bracket</li> <li>2.4 Update to model configuration instructions</li> <li>2.5 Inclusion of the operator sensor mounting instructions on a metal enclosure without a side frame</li> <li>2.6 Update of instructions for sensor guard V2 angle position</li> </ul>			



REV 2.6

Document # DO001205

**Genie Smartlink** 

**Installation Manual** 

### **Important Information**

08/07/2024

Information contained in this publication regarding this device's applications and the like, is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that the application or our equipment meets with your specifications.

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### Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Document # DO001205

#### **Table of Contents**

Preparation	5
Required Tools	5
Installation Time	
Installation Instructions	6
Operator Sensor	6
Control Module	
Post Installation Configuration	
Overview	
Minimum system requirements	
Wi-Fi Connection & Web Page Access	
Machine Model Selection	19
Installation Test	20
Change Model Configuration	21
System Settings	22
Default Parameters	22
Polarity and Input Style	23
Harness Drawing AS001928	24
Replacement Parts	25



### **Preparation**

### **Required Tools**

The OverWatch has been designed to be fitted using basic workshop tools. Shown below is a list of tools required to complete the installation.

Item	Tool / Description
1	Electric Drill
2	Centre Punch
3	Hammer
4	Side Cutters
5	Drill 5.0mm
6	Drill 6.0mm
7	Sockets & Spanners
8	Needle Nose Pliers
9	Screwdrivers
10	Hot glue and hot glue gun

### **Installation Time**

The suggested time required to install the OverWatch is detailed below.

Task	Estimated Time (Minutes)
Open the operator control box	5
Drilling of all mounting holes for the various components	10
Mechanical assembly	10
Electrical assembly	30
Post installation system tests	10
Close the operator control box	5
Total	70



REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Document # DO001205

## **Installation Instructions**

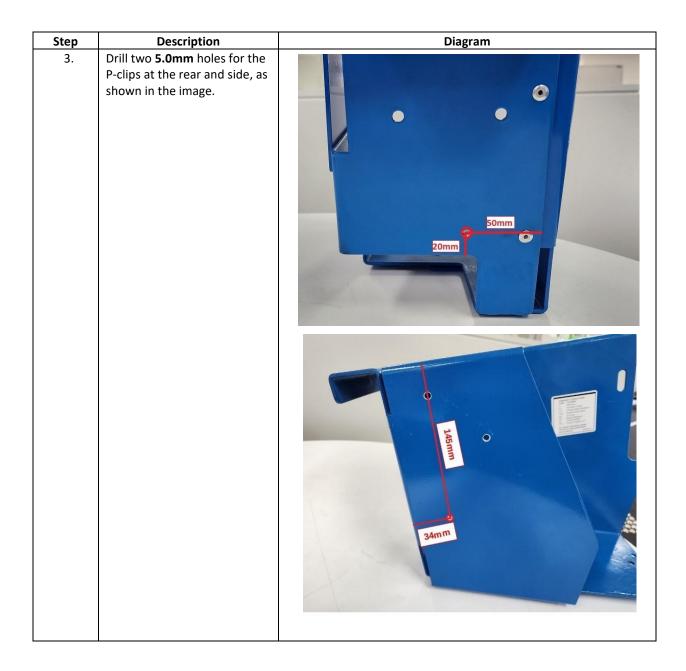
### **Operator Sensor**

Step	Description	Diagram
1.	Remove the Joystick controller from the metal housing.	
2.	Drill two 6mm holes to mount the operator sensor in the position shown in the diagram. Hole #1: 25mm from the top horizontal edge and 34mm from the left vertical edge. Hole #2: 42mm vertically down from the centre of the hole 1 and 45mm horizontal. The distance between the two holes is 61mm. Note: The sensor should be mounted at an angle of 40 degrees from the vertical.	<image/>



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual





## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
4.	If the control box is without a side frame, drill two <b>5.2mm</b> holes to mount the operator sensor mounting bracket as shown in the image. <b>Hole 1: 50mm</b> distance from the top vertical edge to the centre of the hole. <b>Hole 2: 73mm</b> distance from the top vertical edge to the centre of the hole. <b>Note:</b> Make sure to countersunk holes to mount the operator sensor bracket.	<image/>
5.	Mount the operator sensor bracket ( <b>ME001818</b> ) onto the metal enclosure using nuts, bolts and washers. Use the following hardware from the kit. 2 x M5 x 16mm Countersunk Head Screw 2 x M5 Lock Nuts 2 x M5 Washers	



## Genie Smartlink Installation Manual

REV 2.6

08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
6.	Sensor Mounting Guard V1 (ME001794) Mount the operator sensor at a 45-degree angle using the wedges, sensor guard, bolts, and washers.	PARTS LIST ITEM QTY PART NUMBER DESCRIPTION 1 1 AS001910 OverWatch Operator Sensor 2 1 ME001794 OverWatch Operator Sensor Guard 3 2 ME001798 Operator Sensor Alignment Wedge 4 2 FA001422 M4 x 20mm Security Screw 5 2 FA001235 M4 Plain Washer 5 2
	The orientation of the wedge blocks is critical for the correct positioning of the operator sensor. Make sure that the sensor is angled, such that it is <b>twisted outwards</b> from the joystick controller.	
7.	Sensor Mounting Guard V2 (AS002326) This bracket (AS002326) supersedes the original V1 design. Attach the bracket in the 45-degree position using the M5 nuts and washers. Make sure that the sensor is on the 7.5-degree angle, such that it is twisted outwards from the joystick controller.	PARTS LIST         ITEM QTY STOCK NUMBER is DESCRIPTION         1       1       AS002326       Sensor Mounting Guard V2         2       1       AS001910       OverWatch Operator Sensor         3       2       FA001174       Washer, Plain, MS, 304 St. St.         4       2       FA001219       Nut, Hex, MS x 0.8mm, Nylock         Alignment Bolt Installed Here         Alignment Bolt Installed Here         Bottom View
	The 7.5-degree twist is achieved by rotating the sensor inside the assembly and using the bolt hole as show in the image	2     1       3     4       OverWatch 7.5 degree Alignment



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
8.	Route the operator sensor cable as shown in the diagram. Use P-Clips to secure the cable to the metal enclosure.	<image/>





### Genie Smartlink Installation Manual

REV 2.6

08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Document # DO001205

### **Control Module**

Step	Description	Diagram
1.	Remove the bottom plastic cover from the joystick to expose the inside wiring and electronics.	
2.	Remove the buzzer, E- Stop, and the Genie circuit board.	



Model6253 OverWatch<sup>™</sup> Installation Manual

## Genie Smartlink Installation Manual

Step	Description	Diagram
3.	Drill <b>20mm</b> hole to run the operator sensor gland into the plastic joystick enclosure. The position of the hole is detailed as in the image. It is recommended to use a step drill for this hole.	
4.	Use a fine metal pick to clean the area shown in the yellow circles, on the adjacent image, to allow access to the pins and mounting holes. This process removes the conformal coating on the PCB and allows electrical access to the drive, elevate, and horn connections on the circuit board.	



Model6253 OverWatch<sup>™</sup> Installation Manual

## Genie Smartlink Installation Manual

REV 2.6 08/07/2024

Step	Description	Diagram
5.	Use a fine pair of side cutters to trim down the signal pins. These connections must be trimmed to be as flat as possible so that the spring pins from the OverWatch daughter board can make suitable contact.	
6.	Trim down the <b>Elevate</b> signal pin. This pin is located as displayed in the image. Using a fine pair of side cutters make sure that the pin is trimmed flat.	



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
7.	Trim down the <b>Drive</b> signal pin. This pin is located as displayed in the adjacent image. Using a fine pair of side cutters make sure that the pin is trimmed flat.	
8.	Trim down the two <b>Horn</b> signal pins. These pins are located as displayed in the adjacent image. Using a fine pair of side cutters make sure that the pins are trimmed flat.	



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
9.	<ul> <li>Wiring connections are made with the OverWatch harness</li> <li>AS001928.</li> <li>Supplied with the harness is the following hardware:</li> <li>4 x 6.4mm spacers</li> <li>4 x G4x19mm Bolts</li> </ul>	Dugter Board
	These hardware components are critical and must be used to space the daughter board above the Genie circuit board	
10.	Mount the Overwatch daughter board on top of the Genie circuit board by using the provided screws and spacers in the kit. Make sure that the board is sitting in the correct position and the spring pins are contacting the Genie circuit board signal points.	



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
11.	Joystick connection: Install the Overwatch connectors in between the joystick and the Genie circuit board connector. Visually check that all pins from original joystick connector have a corresponding cable on the Overwatch harness. Reconnect the other connectors, which were disconnected in step 2.	
12.	Power Connection:At the back of the E-Stop, install theOverWatch red powercable to terminal 2 ofthe E-Stop.Note: This cable mightneed to be changed toterminal 1 if theOverwatch is poweredwith the E-Stop pushedin.	



## Genie Smartlink Installation Manual

REV 2.6 08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Step	Description	Diagram
13.	Mount the control module in the location shown in the image using the velcro tape. Run the operator sensor cable through the 20mm hole and secure the cable gland. Connect the 8-pin connector from the Operator Sensor and the 12-pin connector from the machine connection	entropy of the second sec
14.	Re-assemble the control	
	Make sure the operator sensor cable runs clear to the joystick and tighten the M20 gland to seal the cable entry point.	



Document # DO001205

**Genie Smartlink** 

## **Post Installation Configuration**

08/07/2024

### **Overview**

After the system has been installed it must be configured with the parameters to suit the machine. Follow the instructions below to configure the OverWatch.

### Minimum system requirements

Any smart phone, tablet or laptop that meets the following requirements:

- The device can connect to a Wi-Fi access point
- The device has an up to date web browser installed. Firefox, Chrome or Safari are recommended. •

### Wi-Fi Connection & Web Page Access

To enable the Wi-Fi connection on the OverWatch to complete the configuration follow the steps below.

- 1. Power down the platform control box with the ESTOP
- 2. Wait 5 seconds
- 3. Power up the platform control box with the ESTOP
- 4. While standing in front of the operator sensor, switch on the OverWatch
- 5. As the welcome chime starts to play, cover the sensor. The LED will flash white then black to acknowledge.
- 6. Remove your hand from the sensor. The LED will flash white then black to acknowledge.
- 7. After covering then uncovering the sensor this way 2 more times, "Wi-Fi On" will be announced
- 8. On your Wi-Fi enabled device (laptop, tablet, smartphone, etc), show the available wireless networks
- 9. Select the wireless network (starts with "overwatch") to connect to the OverWatch
- 10. When prompted, enter the password 12345678
- 11. Open your preferred web browser (Chrome, Firefox, Safari)
- 12. Enter the following into the address bar <u>http://192.168.4.1</u> to open the OverWatch main page



### **Machine Model Selection**

Follow the instructions below to configure the OverWatch.

- 1. Select the Setup option
- 2. If there is a password field at the bottom of the page, follow the instructions in Change Model Configuration to obtain the password and enter the password field
- 3. Select the EWP Model from the drop-down list and click Set
- 4. Click on Proceed to test to begin the installation test

<b>é</b> c	SS	
	OverWatch Setup	
	Genie Smartlink V	
	Set	
	Serial number: 6253E-2004-1234 No control box set.	
	Proceed to test	



### **Installation Test**

After the model configuration has been set or updated an Installation Test must be performed. This will ensure the installation has been correctly performed and the OverWatch is functioning correctly. Follow the instructions on the web page to complete the Installation Test.

qss		
OverWatch Installation	Test	
Joystick	ок	
Elevate	OK	
Drive	OK	
Triager	OK	
Horn	OK	
Cutout	OK	





REV 2.6 08/07/2024

Document # DO001205

### **Change Model Configuration**

To reconfigure the OverWatch for a different model requires an authorisation password. The authorisation password is generated from the EQSS website. The EQSS website requires a login username and password, contact EQSS for these details.

Follow the instructions below to obtain an authorisation password. It is important to note that each ECU has a unique serial number and a unique password.

- 1. Open your web and enter the following into the address bar <a href="http://www.eqss.com.au/overwatch">http://www.eqss.com.au/overwatch</a> to open the Login page
- 2. Enter your username and password
- 3. Enter the EUC serial number which is shown on the setup page or on the ECU serial number sticker, also enter the owner and model details of the EWP and then click Generate Hash
- 4. The generated Hash code or password can be used to change the model configuration.

	John Smith
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	6253E-2004-0000
	Genie Smartlink
	50244



REV 2.6

08/07/2024 Model6253 OverWatch<sup>™</sup> Installation Manual

Document # DO001205

### **System Settings**

### **Default Parameters**

The OverWatch is configurated with the following default parameters.

Setting Name	Description	Default
max_safe_velocity	This is the velocity threshold for the cutout in cm/s for drive mode.	95
max_safe_displacement	This is the maximum permitted distance in cm the operator may be away from the calibration position in drive mode.	50
max_safe_velocity_elevate	This is the velocity threshold for the cutout in cm/s for elevate mode.	75
max_safe_displacement_elevate	This is the maximum permitted distance in cm the operator may be away from the calibration position in elevate mode.	50
fwddispadj	The proportion of the calibration distance toward the sensor permitted to the operator.	0.7
fwdveloadj	The coefficient to apply to the maximum allowable velocity when the movement of the operator is toward the sensor.	1.0
zone_obstruction	If the lidar sensor reading is below this, the lidar is considered to be obstructed (with paint or thick coat of dust) and the system is cutout until the obstruction is cleared.	5
zone_minimum	The minimum calibration distance. If the operator is closer to the sensor than this "operator zone" will be announced.	17
zone_maximum	The maximum calibration distance. If the operator is further from the sensor than this "operator zone" will be announced.	120
adc_elevate_threshold	Threshold value for the elevate ADC input.	100
adc_drive_threshold	Threshold value for the drive ADC input.	100
adc_trigger_threshold	Threshold value for the trigger ADC input.	100
adc_joystick_fwd_threshold	Forward threshold value for the joystick ADC input.	1525
adc_joystick_bwd_threshold	Backward threshold value for the joystick ADC input.	1375
throttle_time	Period after the trigger is pressed (ms) during which initial velocity reading is computed.	500
driving_state_timeout	Mode selection switch timeout (ms)	7000



REV 2.6 08/07/2024

Model6253 OverWatch<sup>™</sup> Installation Manual

Document # DO001205

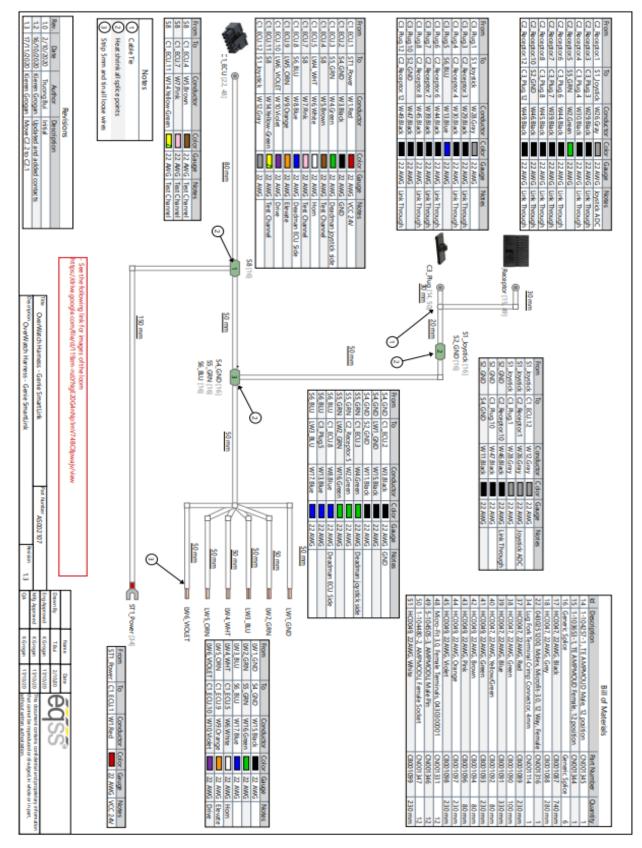
### Polarity and Input Style

The table below describes each setting

Setting Name	Description	Default
joystick_drive_forward	Direction of joystick to move machine forward	forward
joystick_elevate_upward	Direction of joystick to move machine upwards	forward
elevate_polarity	Direction of signal logic	low
drive_polarity	Direction of signal logic	low
trigger_polarity	Direction of signal logic	low
joystick_polarity	Direction of signal logic	high
driving_state_input	Direct or timer based	timer



## Harness Drawing AS001928





### **Replacement Parts**

Replacement parts for this OverWatch kit are available from EQSS, for all inquiries please email <u>sales@eqss.com.au</u> Shown below are the part numbers for the major components included in this model specific kit.

Part Number	Description	
AS001941	OverWatch - Complete kit for Genie Smartlink Series Control Box	
AS001910	OverWatch - Operator Sensor with M20 gland	
AS001916	OverWatch – Electronic Control Unit (ECU)	
AS001928	OverWatch - Genie Smartlink Harness	
AS002326	OverWatch - Sensor Guard V2	
ME001818	OverWatch - L Bracket 30/45	